Recent Advances in Fair Resource Allocation

and

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AAAI 2020 Tutorial on Recent Advances in Fair Resource Allocation – Rupert Freeman and Nisarg Shah

Disclaimer

- In this tutorial, we will <u>NOT</u>
 - > Assume any prior knowledge of fair division
 - > Walk you through tedious, detailed proofs
 - > Claim to present a *complete* overview of the entire fair division realm
 - > Present (recent) unpublished results
- Instead, we will
 - Focus mostly on the case of "additive preferences" for coherence
 O With some results for and pointers to domains with non-additive preferences
- If you spot any errors, missing results, or incorrect attributions:
 > Please email nisarg@cs.toronto.edu or Rupert.Freeman@microsoft.com

Outline

- Fairness Axioms
 - > Proportionality
 - > Envy-freeness
 - > Maximin share guarantee
 - > Groupwise fairness
 - \circ Core
 - Group envy-freeness
 - \circ Groupwise MMS
 - \circ Group fairness

- Implications of fairness
 - > Price of fairness
 - Interplay with strategyproofness and Pareto optimality
 - Restricted cases
- Settings
 - > Cake-cutting
 - > Homogeneous divisible goods
 - > Indivisible goods

A Generic Resource Allocation Framework

- A set of agents $N = \{1, 2, \dots, n\}$
- A set of resources *M*
 - > May be finite or infinite
- Valuations
 - \succ Valuation of agent i is $v_i:2^M \rightarrow \mathbb{R}$

> Range is \mathbb{R}_+ when resources are *goods*, and \mathbb{R}_- when they are *bads*

- Allocations
 - > $A = (A_1, ..., A_n) \in \prod_n(M)$ is a partition of resources among agents ○ $A_i \cap A_j = \emptyset, \forall i, j \in N$ and $\bigcup_{i \in N} A_i = M$

> A partial allocation A may have $\bigcup_{i \in N} A_i \neq M$

Cake Cutting

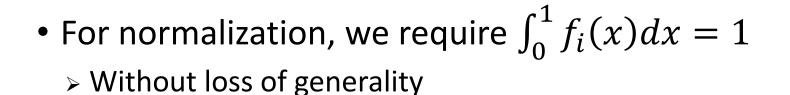
- Formally introduced by Steinhaus [1948]
- Agents: $N = \{1, 2, ..., n\}$
- Resource (cake): M = [0,1]
- Constraints on an allocation A
 - > The entire cake is allocated (full allocation)
 - \succ Each $A_i \in \mathcal{A},$ where \mathcal{A} is the set of finite unions of disjoint intervals
- Simple allocations
 - > Each agent is allocated a single interval
 - > Cuts cake at n-1 points

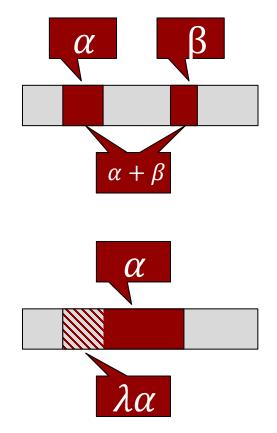


Agent Valuations

• Each agent *i* has an integrable density function $f_i: [0,1] \rightarrow \mathbb{R}_+$

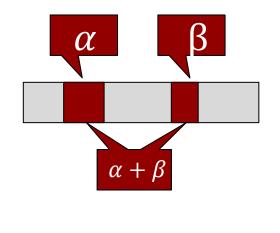
• For each
$$X \in \mathcal{A}$$
, $v_i(X) = \int_{x \in X} f_i(x) dx$

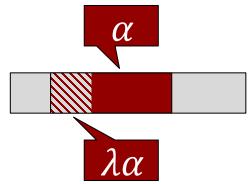




Agent Valuations

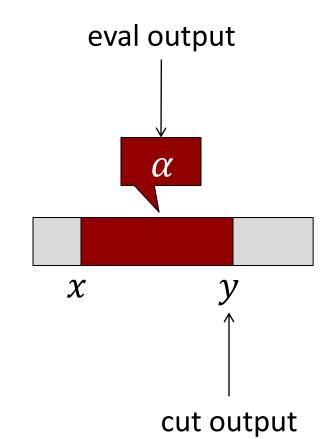
- In this model, the valuations satisfy the following properties
- Normalized: $v_i([0,1]) = 1$
- Divisible: $\forall \lambda \in [0,1]$ and I = [x, y], $\exists z \in [x, y]$ s.t. $v_i([x, z]) = \lambda v_i([x, y])$
- Additive: For disjoint intervals I and I', $v_i(I) + v_i(I') = v_i(I \cup I')$





Complexity

- Inputs are functions
 - Infinitely many bits may be needed to fully represent the input
 - > Query complexity is more useful
- Robertson-Webb Model
 - > $Eval_i(x, y)$ returns $v_i([x, y])$
 - > $\operatorname{Cut}_i(x, \alpha)$ returns y such that $v_i([x, y]) = \alpha$



Three Classic Fairness Desiderata

• Proportionality (Prop): $\forall i \in N$: $v_i(A_i) \geq 1/n$

> Each agent should receive her "fair share" of the utility.

• Envy-Freeness (EF): $\forall i, j \in N : v_i(A_i) \ge v_i(A_j)$

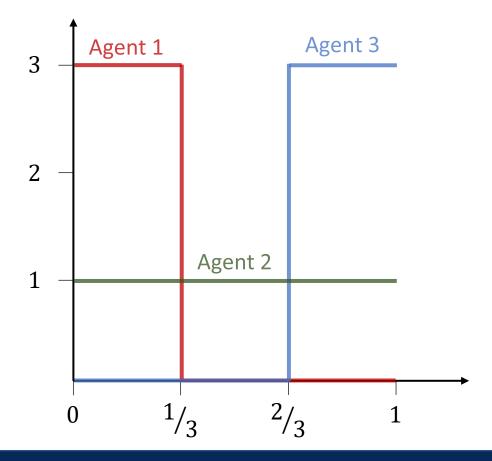
> No agent should wish to swap her allocation with another agent.

• Equitability (EQ): $\forall i, j \in N : v_i(A_i) = v_j(A_j)$

> All agents should have the exact same value for their allocations.

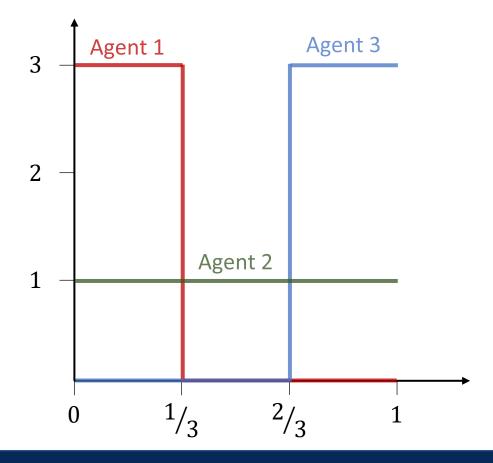
> No agent should be jealous of what another agent received.

• Value density functions



- Agent 1 wants [0, 1/3] uniformly and does not want anything else
- Agent 2 wants the entire cake uniformly
- Agent 3 wants $[2/_3, 1]$ uniformly and does not want anything else

• Value density functions



• Consider the following allocation

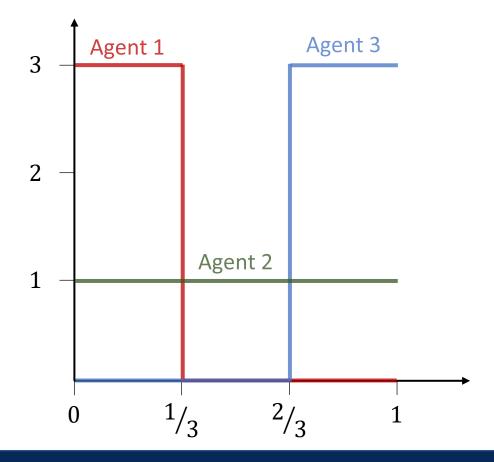
•
$$A_1 = [0, 1/9] \Rightarrow v_1(A_1) = 1/3$$

• $A_2 = [1/9, 8/9] \Rightarrow v_2(A_2) = 7/9$

•
$$A_3 = [\frac{8}{9}, 1] \Rightarrow v_3(A_3) = \frac{1}{3}$$

• The allocation is proportional, but not envy-free or equitable

• Value density functions



• Consider the following allocation

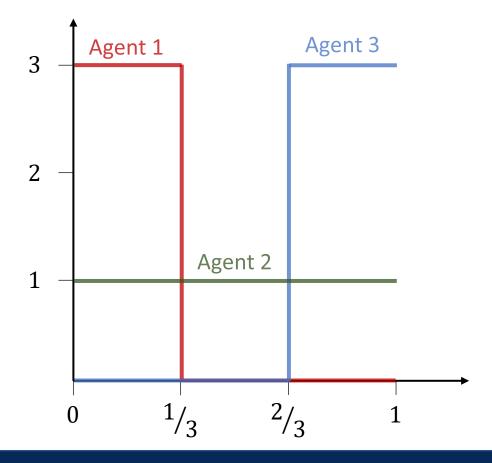
•
$$A_1 = [0, 1/6] \Rightarrow v_1(A_1) = 1/2$$

• $A_2 = [1/6, 5/6] \Rightarrow v_2(A_2) = 2/3$

•
$$A_3 = [5/_6, 1] \Rightarrow v_3(A_3) = 1/_2$$

• The allocation is proportional and envy-free, but not equitable

• Value density functions



• Consider the following allocation

•
$$A_1 = [0, 1/5] \Rightarrow v_1(A_1) = 3/5$$

• $A_2 = [1/5, 4/5] \Rightarrow v_2(A_2) = 3/5$

•
$$A_3 = [4/_5, 1] \Rightarrow v_3(A_3) = 3/_5$$

• The allocation is proportional, envy-free, and equitable

Relations Between Fairness Desiderata

- Envy-freeness implies proportionality
 - > Summing $v_i(A_i) \ge v_i(A_j)$ over all *j* gives proportionality
- For 2 agents, proportionality also implies envy-freeness
 > Hence, they are equivalent.
- Equitability is incomparable to proportionality and envy-freeness
 - E.g. if each agent has value 0 for her own allocation and 1 for the other agent's allocation, it is equitable but not proportional or envy-free.

Existence

• Theorem [Alon, 1987]

Suppose the value density function f_i of each agent valuation v_i is continuous. Then, we can cut the cake at $n^2 - n$ places and rearrange the $n^2 - n + 1$ intervals into n pieces A_1, \ldots, A_n such that

$$v_i(A_j) = 1/n$$
, $\forall i, j \in N$

- This is called a "perfect partition"
 - > It is trivially envy-free (thus proportional) and equitable
- As we will later see, this cannot be found with finitely many queries in Robertson-Webb model

Proportionality

Proportionality : n = 2 Agents

• CUT-AND-CHOOSE

> Agent 1 cuts the cake at x such that $v_1([0, x]) = v_1([x, 1]) = 1/2$

> Agent 2 chooses the piece that she prefers.

• Elegant protocol

- > Proportional (equivalent to envy-freeness for 2 agents)
- > Needs only one cut and one eval query (optimal)
- More agents?

PROPORTIONALITY: DUBINS-SPANIER

• DUBINS-SPANIER

- > Referee starts a knife at 0 and moves the knife to the right.
- Repeat: When the piece to the left of the knife is worth 1/n to an agent, the agent shouts "stop", receives the piece, and exits.
- > When only one agent remains, she gets the remaining piece.
- Can be implemented easily in Robertson-Webb model
 - > When [x, 1] is left, ask each remaining agent *i* to cut at y_i so that $v_i([x, y_i]) = 1/n$, and give agent *i*^{*} ∈ arg min_i y_i the piece [x, y_{i^*}].
- Query complexity: $\Theta(n^2)$

PROPORTIONALITY: EVEN-PAZ

• EVEN-PAZ

• Input:

> Interval [x, y], number of agents n (assume a power of 2 for simplicity)

- Recursive procedure:
 - > If n = 1, give [x, y] to the single agent.
 - > Otherwise:

• Each agent *i* marks z_i such that $v_i([x, z_i]) = v_i([z_i, y])$

 $\circ z^* = (n/2)^{\text{th}}$ mark from the left.

 \circ Recurse on $[x, z^*]$ with the left n/2 agents, and on $[z^*, y]$ with the right n/2 agents.

• Query complexity: $\Theta(n \log n)$

Complexity of Proportionality

- Theorem [Edmonds and Pruhs, 2006]:
 - > Any protocol returning a proportional allocation needs $\Omega(n \log n)$ queries in the Robertson-Webb model.
- Hence, EVEN-PAZ is provably (asymptotically) optimal!

Envy-Freeness

Envy-Freeness : Few Agents

- n = 2 agents : CUT-AND-CHOOSE (2 queries)
- n = 3 agents : SELFRIDGE-CONWAY (14 queries)

Gets complex pretty quickly!

Suppose we have three players P1, P2 and P3. Where the procedure gives a criterion for a decision it means that criterion gives an optimum choice for the player.

- 1. P1 divides the cake into three pieces he considers of equal size.
- 2. Let's call A the largest piece according to P2.
- 3. P2 cuts off a bit of A to make it the same size as the second largest. Now A is divided into: the trimmed piece A1 and the trimmings A2. Leave the trimmings A2 to the side for now.
 - If P2 thinks that the two largest parts are equal (such that no trimming is needed), then each player chooses a part in this order: P3, P2 and finally P1.
- 4. P3 chooses a piece among A1 and the two other pieces.
- 5. P2 chooses a piece with the limitation that if P3 didn't choose A1, P2 must choose it.
- 6. P1 chooses the last piece leaving just the trimmings A2 to be divided.

It remains to divide the trimmings A2. The trimmed piece A1 has been chosen by either P2 or P3; let's call the player who chose it PA and the other player PB.

- 1. PB cuts A2 into three equal pieces.
- 2. PA chooses a piece of A2 we name it A21.
- 3. P1 chooses a piece of A2 we name it A22.
- 4. PB chooses the last remaining piece of A2 we name it A23.

Envy-Freeness : Few Agents

- [Brams and Taylor, 1995]
 - > The first finite (but unbounded) protocol for any number of agents
- [Aziz and Mackenzie, 2016a]

> The first bounded protocol for 4 agents (at most 203 queries)

• [Amanatidis et al., 2018]

> A simplified version of the above protocol for 4 agents (at most 171 queries)

Envy-Freeness

- Theorem [Aziz and Mackenzie, 2016b]
 - > There exists a bounded protocol for computing an envy-free allocation with n agents, which requires $O(n^{n^n^n})$ queries
 - > After O(n²ⁿ⁺³) queries, the protocol can output a partial allocation that is both proportional and envy-free
- What about lower bounds?

Complexity of Envy-Freeness

• Theorem [Procaccia, 2009]

Any protocol for finding an envy-free allocation requires $\Omega(n^2)$ queries.

Open Problem Bridge the gap between $O(n^{n^{n^n}})$ upper bound and $\Omega(n^2)$ lower bound for envy-free cake-cutting

• Theorem [Stromquist, 2008] There is no finite (even unbounded) protocol for finding a simple envy-free allocation for $n \ge 3$ agents.

Equitability

Upper Bound: n = 2 Agents

• Existence

> Suppose we cut the cake at x to form pieces [0, x] and [x, 1]

> Let $f(x) = v_1([0, x]) - v_2([x, 1])$ • Note that f(0) = -1, f(1) = 1, and f is continuous

> By the intermediate value theorem: $\exists x^*$ such that $f(x^*) = 0$

> Allocation $A_1 = [0, x^*]$ and $A_2 = [x^*, 1]$ is equitable

• Theorem [Cechlárová and Pillárová, 2012]

> Using binary search for x^* , we can find an ϵ -equitable allocation for 2 agents with $O(\ln(1/\epsilon))$ queries.

Upper Bound: n > 2 Agents

- Theorem [Cechlárová and Pillárová, 2012]
 - > This technique can be extended to n agents to find an ϵ -equitable allocation in $O(n \ln(1/\epsilon))$ queries.
- Theorem [Procaccia and Wang, 2017]
 - > There exists a protocol for *n* agents which finds an ϵ -equitable allocation in $O(1/\epsilon \ln(1/\epsilon))$ queries.
 - > Intuition:
 - If $n \leq 1/\epsilon$, use above protocol for finding an equitable ϵ -equitable allocation.
 - If $n > 1/\epsilon$, use a variant of the Evan-Paz algorithm to find an *anti-proportional* allocation where $n' = \lfloor 1/\epsilon \rfloor$ agents get value *at most* 1/n', and the rest receive nothing.
 - While this is a "bad" allocation, it is ϵ -equitable.

Lower Bound

- Theorem [Procaccia and Wang, 2017] Any protocol for finding an ϵ -equitable allocation must require $\Omega\left(\frac{\ln(1/\epsilon)}{\ln\ln(1/\epsilon)}\right)$ queries.
- Theorem [Procaccia and Wang, 2017]
 - There is no finite (even if unbounded) protocol for finding an equitable allocation.
 - > Non-existence of bounded protocols follows from the previous result.
 - > But their proof works for non-existence of unbounded protocols as well.

Price of Fairness

Price of Fairness

- Measures the worst-case loss in social welfare due to requirement of a fairness property *X*
- Social welfare of allocation A is the sum of values of the agents > Denoted $sw(A) = \sum_{i \in N} v_i(A_i)$
- Let \mathcal{F} denote the set of feasible allocations and \mathcal{F}_X denote the set of feasible allocations satisfying property X

$$PoF_X = \sup_{v_1, \dots, v_n} \frac{\max_{A \in \mathcal{F}} sw(A)}{\max_{A \in \mathcal{F}_X} sw(A)}$$

Price of Fairness

• Theorem [Caragiannis et al., 2009]

For cake-cutting, the price of proportionality is $\Theta(\sqrt{n})$, and the price of equitability is $\Theta(n)$.

• Theorem [Bertsimas et al., 2011]

For cake-cutting, the price of envy-freeness is also $\Theta(\sqrt{n})$. This is achieved by an allocation maximizing the Nash welfare $\Pi_i v_i(A_i)$.

Fun fact: The price of EF in cake-cutting was mentioned as an open question in a previous version of this tutorial, and was also believed to be open by many groups of researchers until recently.

Efficiency

Efficiency

• Weak Pareto optimality (WPO)

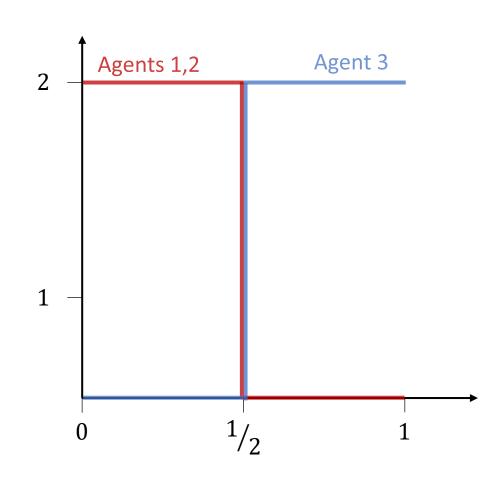
- > Allocation A is weakly Pareto optimal if there is no allocation B such that $v_i(B_i) > v_i(A_i)$ for all $i \in N$.
- "Can't make everyone happier"

• Pareto optimality (PO)

- > Allocation A is Pareto optimal if there is no allocation B such that $v_i(B_i) ≥ v_i(A_i)$ for all agents i ∈ N, and at least one inequality is strict.
- "Can't make someone happier without making someone else less happy"
- > Easy to achieve in isolation (e.g. "serial dictatorship")

PO+EF+EQ: (Non-)Existence

- Theorem [Barbanel and Brams, 2011] With two agents, there always exists an allocation that is envy-free (thus proportional), equitable, and Pareto optimal.
 - > Their algorithm has similarities to the more popular "adjusted winner" algorithm, which we will see later in the tutorial.
- With $n \ge 3$ agents, PO+EQ is impossible



What about PO+EF?

• Competitive Equilibrium from Equal Incomes (CEEI)

> At equilibrium: there is an additive price function P on the cake, and each agent gets to buy their best piece from a budget of one unit of fake currency

> WCE: $\forall i \in N, Z \subseteq [0,1]$: $P(Z) \le P(A_i) \Rightarrow v_i(Z) \le v_i(A_i)$ > EI: $\forall i \in N$: $P(A_i) = 1$

• Theorem [Weller, 1985]

For cake-cutting, a CEEI always exists. Every CEEI is both envy-free and weakly Pareto optimal.

s-CEEI

- Strong Competitive Equilibrium from Equal Incomes (s-CEEI)
 - > A positive slice Z is a subset of the cake valued positively by at least one agent
 - Allocation A is called s-CEEI allocation if there exists an additive price function P satisfying

 > P(Z) > 0 iff Z is a positive slice
 > SCE: ∀i ∈ N, and positive slices Z ⊆ [0,1] and Z_i ⊆ A_i: $\frac{v_i(Z_i)}{P(Z_i)} \ge \frac{v_i(Z)}{P(Z)}$ > EI: ∀i ∈ N: P(A_i) = 1
 Maximum bang-per-buck
 Theorem [Segal-Halevi and Sziklai, 2018] For cake-cutting, an s-CEEI allocation always exists. Every s-CEEI

allocation is envy-free and Pareto optimal.

s-CEEI and Nash-Optimality

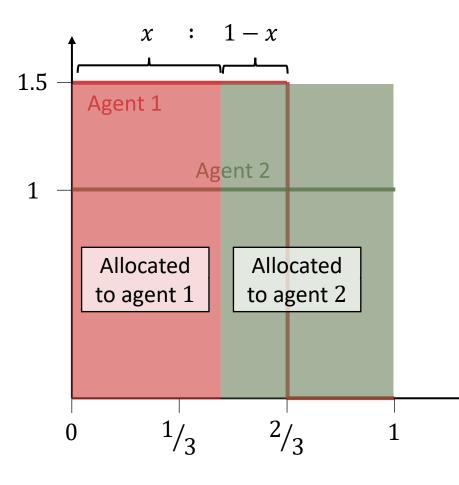
• An allocation A^* is called Nash-optimal if

 $A^* \in \arg \max_A \prod_{i \in N} v_i(A_i)$

• Theorem [Segal-Halevi and Sziklai, 2018]

For cake-cutting, the set of s-CEEI allocations is exactly the same as the set of Nash-optimal allocations.

Nash-Optimality Example



- Due to PO, suppose:
 - > Agent 1 gets x fraction of [0, 2/3]
 - > Agent 2 gets 1 x fraction of [0, 2/3] and all of [2/3, 1]

$$\succ v_1(A_1) = x$$

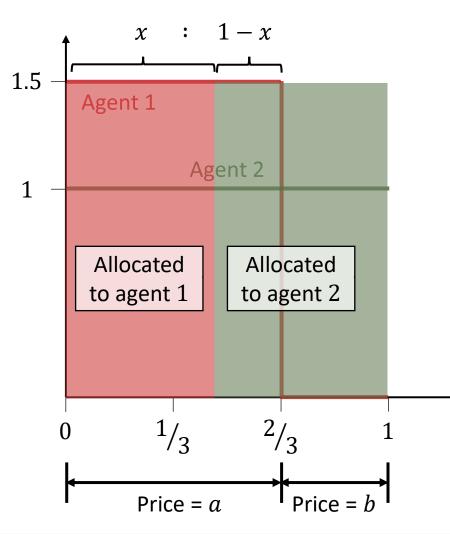
$$> v_2(A_2) = (1 - x) \cdot \frac{2}{3} + \frac{1}{3} = \frac{(3 - 2x)}{3}$$

• Maximize
$$x \cdot \frac{(3-2x)}{3} \Rightarrow x = \frac{3}{4}$$

Nash-optimal allocation:

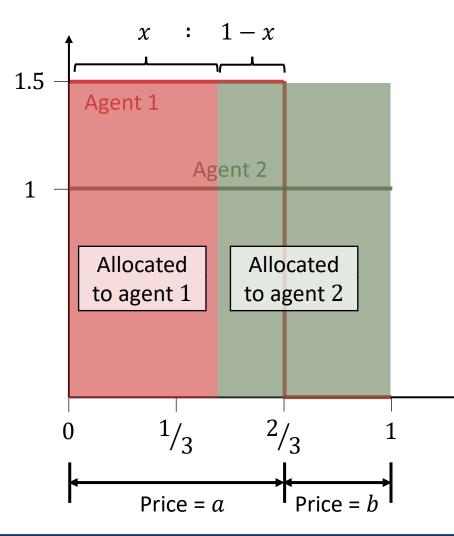
$$\circ A_1 = [0, 1/2], \ v_1(A_1) = 3/4 \circ A_2 = [1/2, 1], \ v_2(A_2) = 1/2$$

Nash-Optimality = s-CEEI



- Still must be PO, so like before
 - > Agent 1 buys x fraction of [0, 2/3]
 - > Agent 2 buys 1 x fraction of [0, 2/3] and all of [2/3, 1]
- Prices: P([0, 2/3]) = a, P([2/3, 1]) = b> Spending: $a \cdot x = 1, a \cdot (1 - x) + b = 1$ \circ Hence, a + b = 2
- Two cases: x < 1 or x = 1

Nash-Optimality = s-CEEI

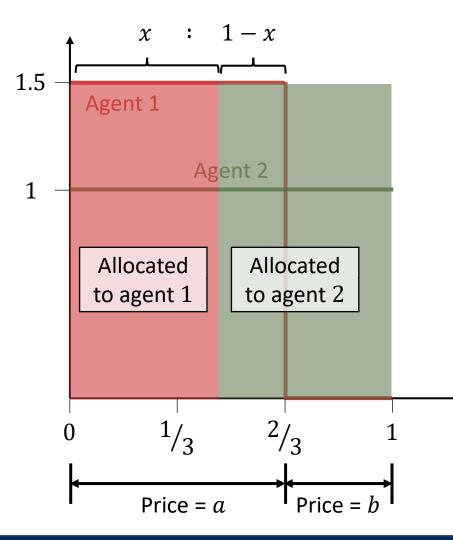


- *x* < 1
 - > Agent 2 buys parts of both pieces> MBB:

$$\frac{1/_{3}}{b} = \frac{2/_{3}}{a} \implies a = 2b \implies (a,b) = (4/_{3}, 2/_{3})$$

> Substituting in $a \cdot x = 1$, we get $x = \frac{3}{4}$ \circ Same as Nash-optimal solution

Nash-Optimality = s-CEEI



•
$$x = 1$$

- > Since $a \cdot x = 1$, $a \cdot (1 x) + b = 1$, we get that a = b = 1
- > Agent 2 buys the second piece, so by MBB:

$$\frac{1/3}{b} \ge \frac{2/3}{a} \implies a \ge 2b$$

Contradiction!

> So there is no s-CEEI with x = 1

Strategyproofness

Strategyproofness (SP)

Direct-revelation mechanisms

> A direct-revelation mechanism h takes as input all the valuation functions v_1, \ldots, v_n , and returns an allocation A

> Notation: $h(v_1, \dots, v_n) = A$, $h_i(v_1, \dots, v_n) = A_i$

- Strategyproofness (deterministic mechanisms)
 - \succ A direct-revelation mechanism h is called strategyproof if

 $\forall v_1, \dots, v_n, \forall i, \forall v'_i : v_i (h_i(v_1, \dots, v_n)) \ge v_i(h_i(v_1, \dots, v'_i, \dots, v_n))$

> That is, no agent i can achieve a higher value by misreporting her valuation, regardless of what the other agents report

Strategyproofness (SP)

- Strategyproofness (randomized mechanisms)
 - Fechnically, referred to as "truthfulness-in-expectation"
 - $\,\circ\,$ When referring to SP for randomized mechanisms, we will refer to this concept
 - > A randomized direct-revelation mechanism h is called strategyproof if $\forall v_1, \dots, v_n, \forall i, \forall v'_i : E[v_i(h_i(v_1, \dots, v_n))] \ge E[v_i(h_i(v_1, \dots, v'_i, \dots, v_n))]$
 - That is, no agent *i* can achieve a higher *expected* value by misreporting her valuation, regardless of what the other agents report
 Expectation is over the randomness of the mechanism

Deterministic SP Mechanisms

- Theorem [Menon and Larson '17, Bei et al. '17] No <u>non-wasteful</u> deterministic SP mechanism is (even approximately) proportional.
 - Since EF is at least as strict as Prop, SP+EF is also impossible subject to nonwastefulness.
 - Non-wastefulness can be replaced by a requirement of "connected pieces", and the impossibility result still holds.

Open Problem

Does the SP+Prop impossibility hold even without the non-wastefulness assumption?

Deterministic SP Mechanisms

- SP+PO is easy to achieve
 - > E.g. serial dictatorship
- SP+PO+EQ is impossible
 - > We saw that even EQ+PO allocations may not exist

Open Problem

Does there exist a direct revelation, deterministic SP+EQ mechanism?

Randomized SP Mechanisms

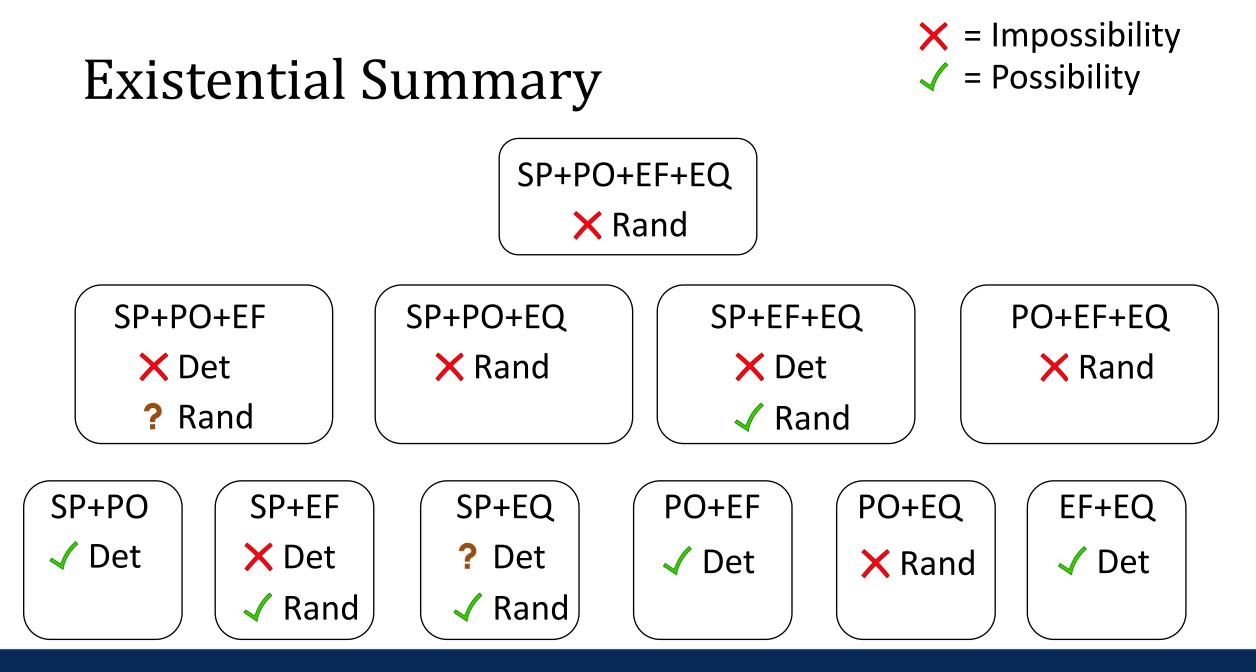
- We want the mechanism *always* return an allocation satisfying a subset of {EQ,EF,PO}, and be SP in expected utilities
- Recall: PO+EQ allocations may not exist
 - > Hence, we can only hope for SP+PO+EF or SP+EF+EQ
 - > The first is an open problem, but the second combination is achievable!

Open Problem

Does there exist a randomized SP mechanism which always returns a PO+EF allocation?

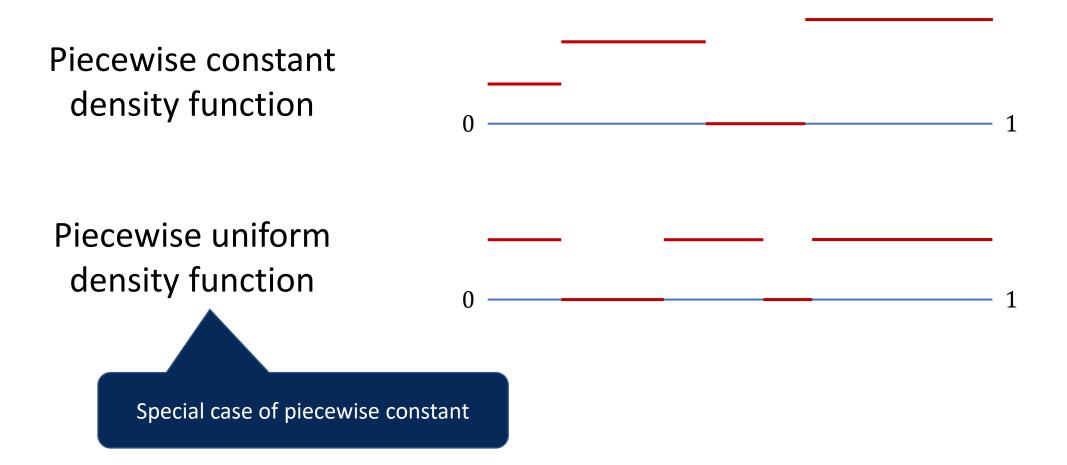
Randomized SP Mechanisms

- Theorem [Mossel and Tamuz, 2010; Chen et al. 2013] There is a randomized SP mechanism that *always* returns an EF+EQ allocation.
 - > Recall: In a perfect partition B, $v_i(B_k) = 1/n$ for all $i, k \in N$
 - Algorithm: Compute a perfect partition and return allocation A which randomly assigns the n pieces to the n agents
 - SP: Regardless of what the agents report, agent *i* receives each piece of the cake with probability 1/n, and thus has expected value exactly 1/n
 - EF: Assuming agents report truthfully (due to SP), agent i always receives a cake she values at 1/n, and according to her, so do others.



Special Cases

Piecewise Constant/Uniform Valuations



Possibilities

• Theorem [Chen et al., 2013]

For piecewise uniform valuations, there exists a deterministic SP mechanism which returns an EF+PO allocation.

> Recall that for general valuations, even deterministic SP+EF is impossible.

• Theorem [Aziz and Ye, 2014]

For piecewise constant valuations, an s-CEEI (i.e. Nash-optimal) allocation can be computed in polynomial time.

- > Recall that this is EF (thus Prop) and PO.
- But this is not SP.

EF in Robertson-Webb

• Theorem [Kurokawa et al., 2013]

If an algorithm computes an envy-free allocation for n agents with piecewise uniform valuations with at most g(n) queries, then it can also compute an envy-free allocation for n agents with general valuations with at most g(n) queries.

- > Let the same algorithm interact with general valuations v_1, \dots, v_n via CUT and EVAL queries and return an allocation A
- > The proof constructs piecewise uniform valuations $u_1, ..., u_n$ which would have resulted in the same responses and $u_i(A_j) = v_i(A_j)$ for all $i, j \in N$

PO in Robertson-Webb

Non-wastefulness

- An allocation A is called non-wasteful if no piece of the cake that is valued positively by at least one agent is assigned to an agent who has zero value for it
- > PO implies non-wastefulness
- Theorem [lanovski, 2012; Kurokawa et al., 2013]

No finite protocol in the Robertson-Webb model can always produce a non-wasteful allocation, even for piecewise uniform valuations.

 This is the reason we did not provide query complexity results when discussing PO

Burnt Cake Division

Model

- Same as regular cake, except agents now have non-positive valuation for every piece of the cake
 - $> f_i(x) \le 0, \forall x \in [0,1]$

≻ Hence, $v_i(X) \le 0, \forall X \in \mathcal{A}$

- Equitability and perfect partitions carry over from the goods case
 - > Simply use $-f_i$ and $-v_i$



Dividing a Burnt Cake

• Theorem [Peterson and Su, 2009]

For burnt cake division, there exists a finite (but unbounded) protocol for finding an envy-free allocation with n agents.

- > Builds upon the Brams-Taylor protocol for dividing a good cake
- But certain operations require non-trivial transformations to the world of chores

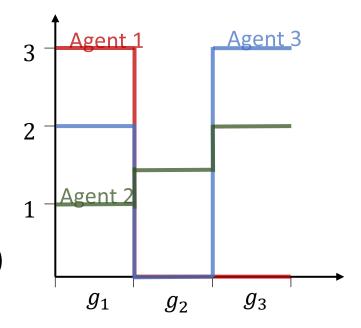
Open Problem

Is there a bounded envy-free protocol for burnt cake division?

(Homogeneous) Divisible Goods

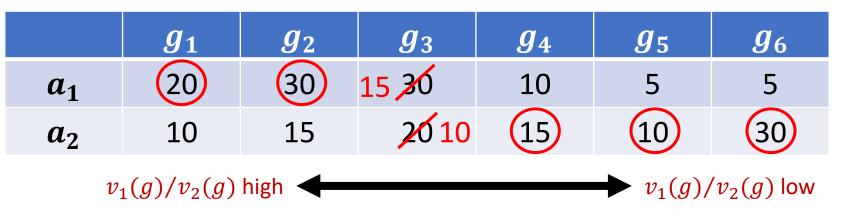
Model

- Agents: $N = \{1, 2, ..., n\}$
- Resource: Set of divisible goods $M = \{g_1, g_2, \dots, g_m\}$
- Allocation $A = (A_1, ..., A_n)$ > $A_i = (A_{i,j})_{j \in [m]}$ > $\forall i, j: A_{i,j} \in [0,1]$ > $\forall j: \sum_i A_{i,j} \leq 1$
- Assume additive valuations $v_i(A_i) = \sum_j A_{i,j} v_i(g_j)$
- Special case of cake cutting (up to normalization)



n = 2: Adjusted Winner Procedure [Brams and Taylor 1996]

- Input: Normalized valuation functions
- Order the goods by ratio $v_1(g)/v_2(g)$.



Divide the goods so that agent 1 receives goods g₁, ..., g_{j-1}, agent 2 receives goods g_{j+1}, ..., g_m for some j, and v₁(A₁) = v₂(A₂)
 > g_j is divided between the agents, if necessary

n = 2: Adjusted Winner Procedure

[Brams and Taylor 1996]

• Theorem [Brams and Taylor 1996]:

> The adjusted winner procedure is envy-free (and therefore proportional), equitable and Pareto optimal

- Breaks down for n > 2
 - > As in cake cutting, EF + EQ + PO is impossible, what about two of the three?
 - > EF+EQ: Divide each good equally among agents ("perfect partition")
 - > EQ + PO: Impossible
 - > EF + PO: Can achieve with CEEI

	${g}_1$	g_2
<i>a</i> ₁	1	0
<i>a</i> ₂	1	0
<i>a</i> ₃	0	1

CEEI

- With a fixed set of items, the definition of s-CEEI (that we will now call just CEEI) becomes simpler.
- Equilibrium price p_j > 0 for each good g_j
 > Assume for simplicity that ∀j ∃i with v_i(g_j) > 0

• CE: If
$$A_{i,j} > 0$$
 then $\frac{v_i(g_j)}{p_j} \ge \frac{v_i(g_k)}{p_k}$ for all k

• EI: $\sum_{j} p_{j} A_{i,j} = 1$ for all i

Eisenberg-Gale convex program

• Can compute a CEEI allocation as the solution to the Eisenberg-Gale [1959] convex program:

$$\begin{aligned} \max \sum_{i \in N} \log u_i \ s.t. \\ \forall i: u_i &\leq \sum_{g_j \in M} A_{i,j} v_i(g_j) \\ \forall j: \sum_{i \in N} A_{i,j} &\leq 1 \\ \forall i, j: A_{i,j} &\geq 0 \end{aligned}$$

• Theorem [Orlin 2010, Végh 2012]:

> The Eisenberg-Gale convex program can be solved in strongly polynomial time.

Strategyproofness

- CEEI solution is fair and efficient but not strategyproof.
 - > It is strategyproof in the large (SP-L) [Azevedo and Budish 2018] though

• Theorem [Han et al. 2011]:

> No strategyproof mechanism that always outputs a complete allocation can achieve better than a 1/m approximation to the optimal social welfare for large enough n.

 \circ Social welfare = $\sum_{i \in N} v_i(A_i)$

• Theorem [Cole et al. 2013]:

- There is a strategyproof partial allocation mechanism that provides every agent with a 1/e fraction of their CEEI utility.
- > Allocation is envy-free but not proportional

SP + Prop + EF

- SP + Prop + EF is trivial! Just allocate everyone an equal fraction of each good.
 - > What if we also want PO?
- Theorem [Schummer 1996]:
 - > It is impossible to achieve SP + Prop + PO.
 - > SP + PO: Serial dictatorship.
- SP + Prop + EF can also be achieved non-trivially [Freeman et al. 2019]
 - > Additionally achieves strict SP: agents always achieve strictly higher utility by reporting their beliefs truthfully than by lying.
 - Exploits a correspondence between fair division and wagering mechanisms [Lambert et al. 2008] to utilize proper scoring rules (e.g. Brier score)

Allocating Divisible Goods + Bads

Model

- Agents: $N = \{1, 2, ..., n\}$
- Resources: Set of divisible "items" $M = \{o_1, o_2, \dots, o_m\}$
- Allocation $A = (A_1, \dots, A_n)$
 - $A_i = (A_{i,j})_{j \in [m]}$ $\forall i, j: A_{i,j} \in [0,1]$ $\forall j: \sum_i A_{i,j} \le 1$
- Assume additive valuations: $v_i(A_i) = \sum_j A_{i,j} v_i(o_j)$ > However, $v_i(o_j)$ can be positive, zero, or negative
- We'll refer to s-CEEI simply as CEEI in this case

Achieving EF+PO

• Theorem [Bogomolnaia et al. 2017]

- > There always exists a CEEI allocation, which is envy-free and Pareto optimal.
- The CEEI solution is "welfarist", i.e., the set of feasible utility profiles is enough to identify the set of CEEI utility profiles.
- > The CEEI utility profile is given by the following:
 - 1. If it is possible to give a positive utility to each agent (who can receive a positive utility), then maximizing the Nash welfare gives the unique CEEI utility profile.
 - 2. Else, if the all-zero utility profile is feasible and Pareto optimal, then it is the unique CEEI utility profile.
 - 3. Else, there can be exponentially many CEEI utility profiles, which give non-positive utility to each agent.
- > Their actual result is stronger and in a more general model

Not Covered

- Nash equilibria of cake-cutting
- Optimal cake-cutting
 - > Algorithms for maximizing social welfare subject to fairness constraints
- Number of cuts and moving knives protocols
 ➤ Possibility and impossibility results for n 1 cuts
- Multidimensional cakes
- Randomized or strategyproof Robertson-Webb protocols
- Non-additive valuations

• ...

Indivisible Goods

Model

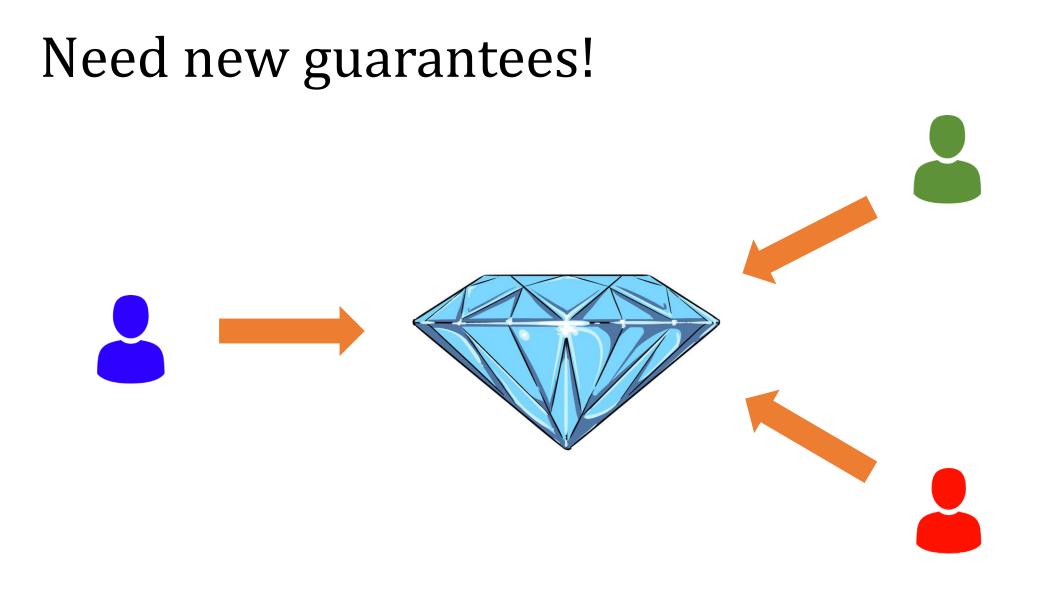
- Agents: $N = \{1, 2, ..., n\}$
- Resource: Set of indivisible goods $M = \{g_1, g_2, \dots, g_m\}$
- Allocation $A = (A_1, ..., A_n) \in \Pi_n(M')$ is a partition of M' for some $M' \subseteq M$.
- Each agent *i* has a valuation $v_i : 2^M \to \mathbb{R}_+$ > $v_i : 2^M \to \mathbb{R}_-$ in the case of bads, $v_i : 2^M \to \mathbb{R}$ for both goods and bads

Valuation Functions

- Additive: $\forall X, Y \text{ with } X \cap Y = \emptyset$: $v_i(X \cup Y) = v_i(X) + v_i(Y)$
 - > Equivalently: $v_i(X) = \sum_{g \in X} v_i(g)$ > Value for a good independent of other goods received

Most results for additive valuations unless stated otherwise

- Submodular: $\forall X, Y : v_i(X \cup Y) + v_i(X \cap Y) \le v_i(X) + v_i(Y)$ > Equivalently: $\forall X, Y$ with $X \subseteq Y : v_i(X \cup \{g\}) - v_i(X) \ge v_i(Y \cup \{g\}) - v_i(Y)$
- Subadditive: $\forall X, Y$ with $X \cap Y = \emptyset$: $v_i(X \cup Y) \le v_i(X) + v_i(Y)$
- Submodular and subadditive definitions capture the idea of diminishing returns.



Envy-Freeness up to One Good

Envy-Freeness up to One Good (EF1) [Lipton et al 2004, Budish 2011]

• An allocation is envy-free up to one good (EF1) if, for all agents i, j, there exists a good $g \in A_i$ for which

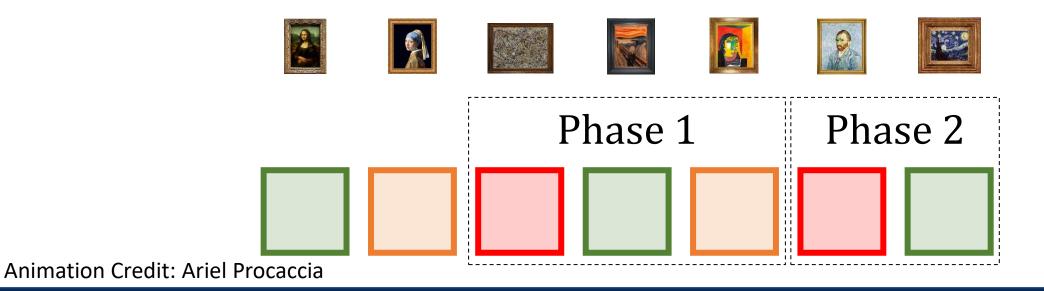
 $v_i(A_i) \ge v_i(A_j \setminus \{g\})$

• "Agent *i* may envy agent *j*, but the envy can be eliminated by removing a single good from *j*'s bundle."

> Note: We don't consider $A_j = \emptyset$ a violation of EF1.

Round Robin Algorithm

- Fix an ordering of the agents σ .
- In round $k \mod n$, agent σ_k selects their most preferred remaining good.
- Theorem: Round robin satisfies EF1.



Algorithm for Achieving EF1

- Envy graph: Edge from *i* to *j* if *i* envies *j*
- Greedy algorithm [Lipton et al. 2004]
 - > One at a time, allocate a good to an agent that no one envies
 - > While there is an envy cycle, rotate the bundles along the cycle.
 - \circ Can prove this loop terminates in a polynomial number of steps
- Removing the most recently added good from an agent's bundle removes envy towards them.
- Neither this algorithm nor round robin is Pareto optimal.

EF1 with Goods and Bads [Aziz et al. 2019]

• An allocation is envy-free up to one item (EF1) if, for all agents i, j, there exists an item $o \in A_i \cup A_j$ for which

 $v_i(A_i \setminus \{o\}) \ge v_i(A_j \setminus \{o\})$

• Round robin fails EF1



Double Round Robin

• Let $O^- = \{o \in O : \forall i \in N, v_i(o) \le 0\}$ denote all unanimous bads and $O^+ = \{o \in O : \exists i \in N, v_i(o) > 0\}$ denote all objects that are a good for some agent.

> Suppose that $|O^-| = an$ for some $a \in \mathbb{N}$. If not, add dummy bads with $v_i(o) = 0$ for all $i \in N$.

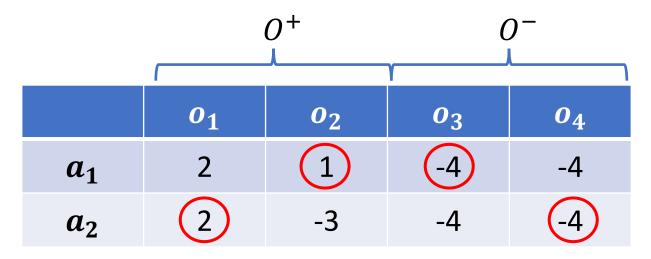
- Double round robin:
 - > Phase 1: O^- is allocated by round robin in order (1, 2, ..., n 1, n)
 - > Phase 2: O^+ is allocated by round robin in order (n, n 1, ..., 2, 1)

> Agents can choose to skip their turn in phase 2

Double Round Robin

• Theorem [Aziz et al. 2019]:

- The double round robin algorithm outputs an allocation that is EF1 for combinations of goods and bads in polynomial time.
- Proof idea: Let i < j. Agent i can envy j up to one item in phase 1 (but not vice versa), and agent j can envy i up to one item in phase 2 (but not vice versa)</p>



Maximum Nash Welfare

• Maximum Nash Welfare (MNW): Select the allocation that maximizes the geometric mean of agent utilities (more on this later).

$$A = \arg \max \left(\prod_{i} v_i(A_i) \right)^{1/2}$$

> This is just Nash-optimality from earlier

- What if $\prod_i v_i(A_i) = 0$ for all allocations?
 - > Find an allocation that maximizes $|\{v_i(A_i) > 0\}|$, and subject to that maximizes

$$\left(\prod_{i:v_i(A_i)>0}v_i(A_i)\right)^{1/n}$$

EF1 + PO

• Theorem [Caragiannis et al. 2016]:

- > The MNW allocation satisfies EF1 and PO.
- > PO: A Pareto-improving allocation would have higher geometric mean of utilities for agents with non-zero utility or more agents with non-zero utility.
- > EF1: Let $g_i^* = \arg \max_{g \in A_i} v_i(g)$. Not-too-hard proof shows $v_j(A_j) \ge v_j(A_i \setminus g_i^*)$ for all j.

	g_1	${oldsymbol{g}}_2$	g_3	${g}_4$	$oldsymbol{g}_{5}$	${oldsymbol{g}}_{6}$
a_1	2		3	0	1	2
a_2	10	1	1		2	5
a_3	3	1	3	0	5	2

Computing EF1 + PO

- The MNW allocation is strongly NP-hard to compute (reduction from X3C).
 - > Actually, it's APX-hard [Lee 2017].

- Special case: Binary valuations
 - > MNW allocation can be computed in polynomial time [Darmann and Schauer 2015, Barman et al. 2018].
 - > However, round robin already guarantees EF1 + PO in this setting.

Computing EF1 + PO

• Theorem [Barman et al. 2018]:

- > There exists a pseudo-polynomial time algorithm for computing an allocation satisfying EF1 + PO
- Algorithm uses local search (sequence of item swaps and price rises) to compute an integral competitive equilibrium that is price envy-free up to one good.
- > Price envy-free up to one good: $\forall i, k, \exists j: p(A_i) \ge p(A_k \setminus \{g_j\})$
- Need different entitlements because CEEI might not exist with indivisibilities
 Two agents, one item...

Computing EF1 + PO

Open Problem: Complexity of computing an EF1 + PO allocation

Open Problem: Does there always exist an EF1 + PO allocation for submodular valuation functions?

EF1 + PO for Bads

• Theorem [Aziz et al. 2019]:

> When items can be either goods or bads and n = 2, an EF1 + PO allocation always exists and can be found in polynomial time

Open Problem: Does an EF1 + PO allocation always exists for bads?

Proportionality up to One Good

Proportionality up to One Good (Prop1) [Conitzer et al. 2017]

• An allocation is proportional up to one good (Prop1) if, for every agent *i*, there exists a good *g* for which

$$v_i(A_i \cup \{g\}) \ge \frac{v_i(M)}{n}$$

	${oldsymbol{g}}_1$	${oldsymbol{g}}_2$	g_3
<i>a</i> ₁	1	3	3
a_2	1	3	3

$$v_1(A_1 \cup \{g_2\}) = 4 \ge \frac{7}{2} = \frac{v_i(M)}{n}$$

Prop1 + PO

- Any algorithm that satisfies EF1 + PO is also Prop1 + PO.
 - > MNW
 - > Barman et al. [2018] algorithm
- Theorem [Barman and Krishnamurthy 2019]:
 - > An allocation satisfying Prop1 + PO can be computed in strongly polynomial time.
- Allocation is a careful rounding of the fractional CEEI allocation.
 - In contrast, there exist instances in which no rounding of the fractional CEEI allocation will give EF1 [Caragiannis et al., 2016].

Envy-Freeness up to the Least Valued Good

Envy-Freeness up to the Least Valued Good [Caragiannis et al. 2016]

	${oldsymbol{g}}_1$	${oldsymbol{g}}_2$	g_3
a_1	10	5	5
<i>a</i> ₂	10	ϵ	ϵ

• An allocation is envy-free up to the least valued good (EFX) if, for all agents i, j, and every $g \in A_j$ with $v_i(g) > 0$,

$$v_i(A_i) \ge v_i(A_j \setminus \{g\}).$$

Leximin Allocation

• Leximin allocation:

> First, maximize the minimum utility any agent receives. Subject to this, maximize the second-minimum utility. Then the third-minimum utility, etc.

	${oldsymbol{g}}_1$	${oldsymbol{g}}_2$	${oldsymbol{g}}_3$	${g}_4$	${m g}_5$	${oldsymbol{g}}_{6}$
a_1	2	1	3	0	1	2
<i>a</i> ₂	10	1	1		2	5
<i>a</i> ₃	3	1	3	0	5	2

Satisfying EFX

	g_1	g_2	g_3	g_4
<i>a</i> ₁	4	1	2	2
a_2	4	1	2	2
a_3	4	1	2	2

- Theorem [Plaut and Roughgarden, 2018]:
 - > The Leximin allocation satisfies EFX + PO for agents with (general) identical valuations.
- Theorem [Plaut and Roughgarden, 2018]:
 - The Leximin allocation satisfies EFX + PO for two agents with (normalized) additive valuations.

Open Problem:

Does there always exist a complete allocation satisfying EFX?

Satisfying EFX

- What about partial allocations satisfying EFX?
 - > Easy! We can just throw all goods away and take the empty allocation.

• Theorem [Caragiannis et al. 2019]:

- > There exists a partial allocation that satisfies EFX and achieves a 2approximation to the optimal Nash welfare.
- > No (complete or partial) EFX allocation can achieve a better approximation.

	Exist	tence	Computation		
	Without PO	ithout PO With PO Without PO		With PO	
Envy-Freeness	No	Νο	NP-hard	NP-hard	
EFX	Open	Open	Open	Open	
EF1	Yes	Yes	Polytime	Open	
Prop1	Yes	Yes	Polytime	Polytime	

Maximin Share

Maximin Share [Budish 2011]

• "If I partition the goods into *n* bundles and receive an adversarially chosen bundle, how much utility can I guarantee myself?"

• Define
$$MMS_i^k(S) = \max_{\substack{(P_1,\dots,P_k)\in\Pi_k(S) \\ 1 \le j \le k}} \min_{\substack{1 \le j \le k}} v_i(P_j)$$

• MMS allocation: One for which $v_i(A_i) \ge MMS_i^n(M)$

• Note that
$$MMS_i^n(M) \leq \frac{v_i(M)}{n}$$
, so Proportionality implies MMS

Maximin Share [Budish 2011]



$$MMS_1^n(M) = \min(3,3,3) = 3$$
$$MMS_2^n(M) = \min(10,5,5) = 5$$
$$MMS_3^n(M) = \min(4,5,5) = 4$$

Achieving Maximin Allocations

• Theorem [Procaccia and Wang 2014]:

- > There exist instances for which no allocation satisfies MMS.
- Instead, consider approximations.
 - > c-MMS: allocation for which $v_i(A_i) \ge c \cdot MMS_i^n(M)$
 - > Guarantee $v_i(A_i) \ge MMS_i^k(M)$ for some k > n

• Theorem [Budish 2011]:

> There always exists an allocation that satisfies $v_i(A_i) \ge MMS_i^{(n+1)}(M)$ for every agent *i*.

c-MMS Allocations

• Theorem [Procaccia and Wang 2014]:

> A (2/3)-MMS allocation always exists.

• Theorem [Amanatidis et al. 2017]:

> A (2/3- ϵ)-MMS allocation can be computed in polynomial time.

- Theorem [Ghodsi et al. 2018]:
 - > A (3/4)-MMS allocation always exists and a (3/4- ϵ)-MMS allocation can be computed in polynomial time.

c-MMS Allocations

[Ghodsi et al. 2018]

	Additive	Submodular	Subadditive
Lower bound (existence)	$\frac{3}{4}$	$\frac{1}{3}$	$\frac{1}{10} \lceil \log m \rceil$
Lower bound (polynomial algorithm)	$\frac{3}{4} - \epsilon$	$\frac{1}{3}$	-
Upper bound	$1-\frac{1}{n^{n}+1}$	$\frac{3}{4}$	$\frac{1}{2}$

Open Problem:	
Close the gaps!	

c-MMS Allocations for Bads

• Theorem [Aziz et al. 2017]:

> A 2-MMS allocation always exists and can be computed in polynomial time when dividing bads.

• Theorem [Barman and Krishnamurthy 2017]:

> A (4/3)-MMS allocation always exists and can be computed in polynomial time when dividing bads.

Groupwise MMS [Barman et al. 2018]

 Idea: MMS_i^k should be guaranteed for all groups J of agents of size k and set of goods U_{i∈J} A_i

	${g}_1$	${oldsymbol{g}}_2$	g ₃	${g}_4$	${m g}_5$	${oldsymbol{g}}_{6}$
a_1	5	5	$5 + \epsilon$	$5-\epsilon$	5 + <i>e</i>	$5-\epsilon$
<i>a</i> ₂	5	5	$5+\epsilon$	$5-\epsilon$	5 + <i>ε</i>	$5-\epsilon$
<i>a</i> ₃	10	10	0	0	ϵ	ϵ

•
$$v_3(A_3) \ge MMS_3^3(M)$$
 but $v_3(A_3) < MMS_3^2(A_1 \cup A_3)$

Groupwise MMS [Barman et al. 2018]

• Allocation A satisfies Groupwise Maximin Share (GMMS) if,

$$\forall i: v_i(A_i) \ge \max_{J \subseteq N} MMS_i^{|J|}(\bigcup_{j \in J} A_j)$$

- Theorem [Barman et al. 2018]:
 - > When valuations are additive, a 0.5-GMMS allocation exists and can be found in polynomial time.
 - > Algorithm: Select an agent who is not envied by any other agent, and allocate her her most preferred unallocated good.
 - Small refinement of EF1 algorithm from earlier

(Relaxed) Equitability

Equitability

• Recall equitability:

$$\forall i, j \in N: v_i(A_i) \ge v_j(A_j)$$

- We can relax it in the same way we did for envy-freeness [Gourves et al. 2014, Freeman et al. 2019].
- Equitability up to one good (EQ1):

$$\forall i, j \in N, \exists g \in A_j : v_i(A_i) \ge v_j(A_j \setminus \{g\})$$

• Equitability up to any good (EQX):

$$\forall i, j \in N, \forall g \in A_j : v_i(A_i) \ge v_j(A_j \setminus \{g\})$$

Algorithm for Achieving EQX

• Greedy Algorithm [Gourves et al. 2014]:

> Allocate to the lowest-utility agent the unallocated good that she values the most.

• Almost the same as EF1 algorithm, but achieves EQX!

Compare to EFX, existence still unknown

EQ1/EQX + PO

• Theorem [Freeman et al. 2019]:

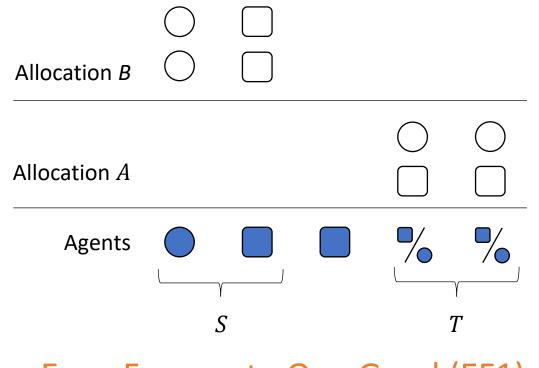
- > An allocation satisfying EQ1 and PO may not exist.
- Compare to EF1 + PO always exists

	${g}_1$	${g}_2$	g_3	g_4	${m g}_5$	${oldsymbol{g}}_{6}$
a_1			1	0	0	0
a_2	0	0	0	1	1	1
a_3	0	0	0	1	1	

- Theorem [Freeman et al. 2019]:
 - > When valuations are strictly positive, the Leximin allocation is EQX + PO

Group Fairness

Beyond Individual Fairness



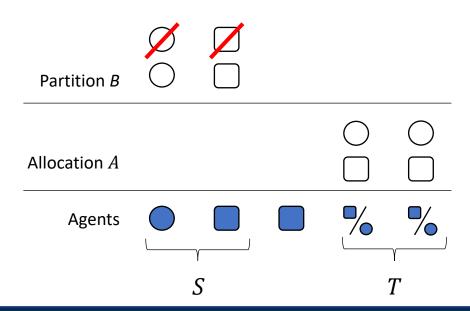
Envy-Free up to One Good (EF1)

Group Fairness

- An allocation A is group fair if for every non-empty $S, T \subseteq N$ and every partition $(B_i)_{i \in S}$ of $\bigcup_{j \in T} A_j$, $\left(\frac{|S|}{|T|}\right) \cdot (v_i(B_i))_{i \in S}$ does not Pareto dominate $(v_i(A_i))_{i \in S}$
- "It should not be possible to redistribute the goods allocated to group T amongst group S in such a way that every member of group S is (weakly, with at least one strictly) better off, with utilities adjusted for group sizes"
- Group Fairness \Rightarrow EF + PO

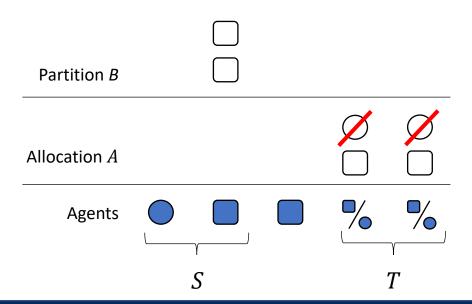
Group Fairness Relaxations

- Group Fairness up to One Good, After (GF1A) [Conitzer et al. 2019]
 - "It should not be possible to redistribute the goods allocated to group T amongst group S in such a way that every member of group S is (weakly, with at least one strictly) better off, even when one good is removed from each agent in S, with utilities adjusted for group sizes"



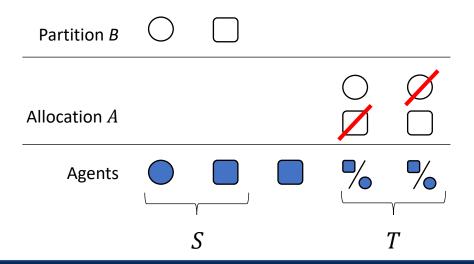
Group Fairness Relaxations

- Group Fairness up to One Good, Before (GF1B) [Conitzer et al. 2019]
 - It should not be possible to redistribute the goods allocated to group T, with one good per agent in T removed, amongst group S in such a way that every member of group S is (weakly, with at least one strictly) better off, with utilities adjusted for group sizes"



Group Fairness Relaxations

- Group Fairness up to One Good, Before (GF1B) [Conitzer et al. 2019]
 - It should not be possible to redistribute the goods allocated to group T, with one good per agent in T removed, amongst group S in such a way that every member of group S is (weakly, with at least one strictly) better off, with utilities adjusted for group sizes"



Achieving GF1A/GF1B

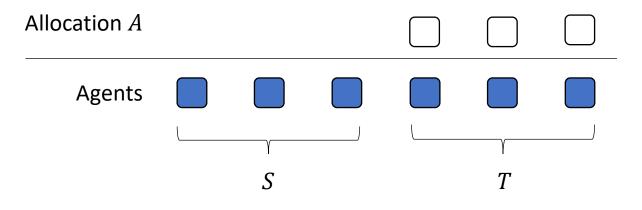
- Locally Nash-optimal allocation: Product of utilities cannot be improved by moving a single good.
 - $\forall i, j, g \in A_j: v_j(g) > 0 \text{ and } v_i(A_i) \cdot v_j(A_j) \ge v_i(A_i + g) \cdot v_j(A_j g)$
- Theorem [Conitzer et al. 2019]:
 - > Any locally Nash-optimal allocation satisfies GF1A and GF1B.
 - > Can be computed in pseudo-polynomial time by local search
 - > When valuations are identical, an allocation is locally Nash-optimal iff it is EFX/EQX.

Open Problem:

Can we compute a locally Nash-optimal allocation in polynomial time?

Known Groups

• When we want to provide guarantees for **all** subsets of agents, "up to one good per agent" guarantees are the best we can give.



Open Problem:

Can we give stronger guarantees when S and T are fixed in advance?

- We have seen that MNW satisfies several nice properties.
 - > GF1A/B (\Rightarrow EF1) + PO
 - Scale-free
 - > Natural fairness/efficiency tradeoff
- But NP-hard to optimize. Can we approximate?

• Theorem [Lee 2017]

- Computing an allocation that maximizes the geometric mean of agent utilities under additive valuation functions is APX-hard.
- > Approximating to within a factor of 1.00008 is NP-hard.

- Theorem [Cole and Gkatzelis 2015, Cole et al 2017]:
 - There exists a polynomial time algorithm that approximates the MNW objective to within a constant multiplicative factor of 2.
- Theorem [Barman et al. 2018]:
 - > There exists a polynomial time algorithm that approximates the MNW objective to within a constant multiplicative factor of 1.45.

Open Problem:

Close the gap between the 1.00008 lower bound and 1.45 upper bound.

- Approximate MNW solutions may not retain the nice properties of the exact solution.
- Theorem [Garg and McGlaughlin 2019]:
 - There exists a polynomial time algorithm that approximates the MNW objective to within a constant multiplicative factor of 2 and achieves Prop1, (1/2n)-MMS and PO.
- And recall, there exists a partial allocation that satisfies EFX and is a 2-approximation to MNW objective [Caragiannis et al 2019].

- What effect does requiring a fairness property have on the social welfare?
- Price of Fairness [Bertsimas et al. 2011, Caragiannis et al. 2012]:
 - The price of fairness of fairness property P is defined as the ratio of the maximum possible social welfare and the maximum social welfare of an allocation that satisfies P.
- Strong Price of Fairness [Bei et al. 2019]:
 - The strong price of fairness of fairness property P is defined as the ratio of the maximum possible social welfare and the minimum social welfare of an allocation that satisfies P.
- Cf. Price of Stability and Price of Anarchy

• Theorem [Caragiannis et al. 2012]:

> The price of fairness for proportionality, envy-freeness and equitability are:

	Indivisible Goods	Cake Cutting
Proportionality	$\Theta(n)$	$\Theta(\sqrt{n})$
Envy-freeness	$\Theta(n)$	$\Theta(\sqrt{n})$
Equitability	∞	$\Theta(n)$

• Caragiannis et al. also studied divisible items, and bads.

• Theorem [Bei et al. 2019]:

> Bounds on the (strong) price of fairness for indivisible goods

	Price of P	Strong Price of P
EF1	LB: $\Omega(\sqrt{n})$, UB: $O(n)$	∞
Round Robin	n	n^2
Max Nash Welfare	$\Theta(n)$	$\Theta(n)$
Leximin	$\Theta(n)$	$\Theta(n)$
Pareto optimality	1	$\Theta(n^2)$

Open Problem: Close the gap for EF1

Strategyproofness

Adding Strategyproofness

- None of the rules we have considered so far are strategyproof
- For divisible goods, structure of strategyproof mechanisms is fairly rich
 - > Impossibilities from the divisible realm carry over
- What about indivisible goods?

	${oldsymbol{g}}_1$	${oldsymbol{g}}_2$	g_3
<i>a</i> ₁	1	x	0
<i>a</i> ₂	0	У	1

[Amanatidis et al. 2017]

• Picking Mechanism:

- ≻ Partition $M = N_1 \cup N_2$
- > Agent 1 receives a subset of offers $O_1 \subseteq 2^{N_1}$. Let $S_1 = \arg \max_{S \in O_1} v_1(S)$.
- > Agent 2 receives a subset of offers $O_2 \subseteq 2^{N_2}$. Let $S_2 = \arg \max_{S \in O_2} v_2(S)$. > $A_1 = S_1 \cup (N_2 \setminus S_2)$ and $A_2 = S_2 \cup (N_1 \setminus S_1)$

•
$$N_1 = \{g_1, g_2, g_3, g_4\}, N_2 = \{g_5, g_6\}$$

•
$$O_1 = \{\{g_1, g_2\}, \{g_2, g_3\}, \{g_4\}\}, O_2 = \{\{g_5\}, \{g_6\}\}$$

	$oldsymbol{g}_1$	${oldsymbol{g}}_2$		$oldsymbol{g}_4$	${oldsymbol{g}}_5$	${oldsymbol{g}_6}$
<i>a</i> ₁	3	5	5	10	4	2
a_2	2	3	6	1	5	3

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[Amanatidis et al. 2017]

• Exchange Mechanism:

- ≻ Partition $M = E_1 \cup E_2$
- > Set of exchange deals $D = \{(S_1, T_1), \dots, (S_k, T_k)\}$, where each $(S, T) \subseteq (E_1, E_2)$
- Solution Agent i receives allocation E_i by default, with exchanges performed if they are mutually beneficial
- $E_1 = \{g_1, g_2, g_3\}, E_2 = \{g_4, g_5\}$
- $D = \{(\{g_2, g_3\}, \{g_4\})\}$



[Amanatidis et al. 2017]

• Picking-Exchange Mechanism: Run a picking mechanism on $N_1 \cup N_2 \subseteq M$ and an exchange mechanism on $E_1 \cup E_2 \subseteq M$, where $N_1 \cup N_2 \cup E_1 \cup E_2 = M$ and N_1, N_2, E_1, E_2 are pairwise disjoint.

> Up to tiebreaking technicalities...

[Amanatidis et al. 2017]

• Theorem [Amanatidis et al. 2017]:

- For n = 2 an allocation mechanism that allocates all goods is strategyproof if and only if it is a picking-exchange mechanism
- Corollary [Amanatidis et al. 2017]:
 - For n = 2, any strategyproof mechanism that allocates all goods does not achieve any positive approximation of the minimum envy or best proportionality guarantee.
 - > For n = 2 and $m \ge 5$, no strategy proof mechanism can allocate all items and satisfy EF1.
 - > For n = 2, no strategyproof mechanism guarantees better than $\frac{1}{|m/2|}$ -MMS.

• This is a tight bound [Amanatidis et al. 2016]

More General Strategyproof Mechanisms

Open Problem:

What is the structure of strategy proof mechanisms for n = 2 when not all goods have to be allocated?

Open Problem:

What is the structure of strategyproof mechanisms for n > 2?

What's Not Covered

- Envy-freeness up to one less-preferred item (EFL) [Barman et al. 2018]
 - > Stronger than EF1 and guaranteed to exist
 - > Existence of EFL + PO allocations is an open question
- Various constraints and additional features
 - > Agent social network structure
 - Connectivity constraints when items lie on a graph
- Asymptotic results
- •

Ordinal Preferences

Ordinal Preferences

- Instead of valuation functions, take in preference orderings ≽_i over items
 - \succ E.g. $g_2 \geq_i g_3 \geq_i g_1 \geq_i g_4$
- Agents are assigned fractions of each item
 - $\succ A = (A_{i,j})_{i \in [n], j \in [m]}$

> Can be interpreted as lotteries over integral allocations

Ordinal Preferences

 Partial preferences over bundles defined via stochastic dominance extension

$$A \geq_{i}^{SD} B$$
 iff $\forall k : \sum_{j \geq_{i} k} A_{i,j} \geq \sum_{j \geq_{i} k} B_{i,j}$

- Many other extensions possible
 - > Upper/downward lexicographic [Cho 2012]
 - Pairwise comparison [Aziz et al. 2014]
 - > Bilinear dominance [Aziz et al. 2014]
- Can also elicit ordinal information over subsets directly [Bouveret et al. 2010]

Two Mechanisms

Random Priority

- > Select a random ordering of the agents. Agents select their favorite m/n goods in order.
- Probabilistic Serial [Bogomolnaia and Moulin 2001]

> Agents "eat" at a constant (equal) rate. At any time, agents eat their most preferred good that is not completely consumed.

•
$$\geq_1$$
: $g_1 \geq_1 g_2 \geq_1 g_3 \geq_1 g_4$
Random Priority

	${g}_1$	g_2	g_3	g_4
<i>a</i> ₁	1	1/2	0	1/2
<i>a</i> ₂	0	1/2	1	1/2

$$\succcurlyeq_2: g_2 \succcurlyeq_2 g_3 \succcurlyeq_2 g_1 \succcurlyeq_2 g_4$$
Probabilistic Serial

	g_1	g_2	g_3	${g}_4$
a_1	1	0	1/2	1/2
<i>a</i> ₂	0	1	1/2	1/2

SD-efficiency

- SD-efficiency: There should not exist an alternative allocation that all agents weakly prefer and some agent strictly prefers.
- Theorem [Bogomolnaia and Moulin 2001]:

> Probabilistic Serial satisfies SD-efficiency

• Random Priority is not SD-efficient

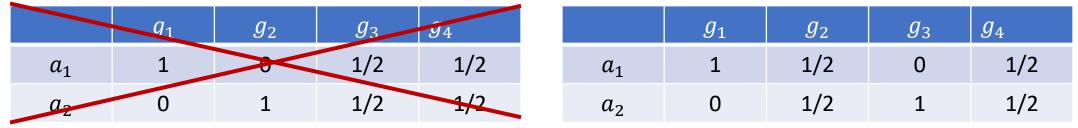
 $\succcurlyeq_1: g_1 \succcurlyeq_1 g_2 \succcurlyeq_1 g_3 \succcurlyeq_1 g_4 \qquad \qquad \succcurlyeq_2: g_2 \succcurlyeq_2 g_1 \succcurlyeq_2 g_4 \succcurlyeq_2 g_3$

	${g}_1$	g_2	g_3	${\cal g}_4$
<i>a</i> ₁	1/2	1/2	1/2	1/2
<i>a</i> ₂	1/2	1/2	1/2	1/2

SD-strategyproofness

- SD-strategyproofness: No agent should be able to improve their allocation by misreporting their preferences.
- Theorem:
 - Random Priority is SD-strategyproof.
- Probabilistic Serial is not SD-strategyproof

$$\geqslant_1: \underbrace{g_1 \geq_1 g_2}_{g_1 \geq_1} g_3 \geq_1 g_4 \qquad \qquad \geqslant_2: g_2 \geq_2 g_3 \geq_2 g_1 \geq_2 g_4 \\ g_2 \geq_1 g_1$$



SD-Efficiency + SD-Strategyproofness

- Theorem [Bogomolnaia and Moulin 2001]:
 - No mechanism satisfies SD-efficiency, SD-strategyproofness, and equal treatment of equals
- We can get SD-efficiency + SD-envy-freeness
 - > SD-envy-freeness: $\forall i, j: \sum_{j=1}^{m} A_{i,j}g_j \geq_i^{SD} \sum_{j=1}^{m} B_{i,j}g_j$
 - > Probabilistic Serial is SD-envyfree

Public Decisions

Public Decisions Model

- Set of agents N
- Set of issues T
- Each issue has associated set of alternatives $C^t = \{c_1^t, \dots, c_{k_t}^t\}$
- Agents have utility functions $u_i^t: A^t \to \mathbb{R}_+$

	lssue 1			lssue 2					lssue T	-
	c_1^1	c_{2}^{1}	c_3^1	c_{1}^{2}	c_{2}^{2}	c_{3}^{2}		c_1^T	c_2^T	c_3^T
<i>a</i> ₁	3	1	0	2	5	1	•••	6	5	5
<i>a</i> ₂	2	2	1	3	4	1		2	4	3
a_3	0	0	4	4	3	2		5	4	5

Public Decisions Model

- Set of agents N
- Set of issues T
- Each issue has associated set of alternatives $C^t = \{c_1^t, \dots, c_{k_t}^t\}$
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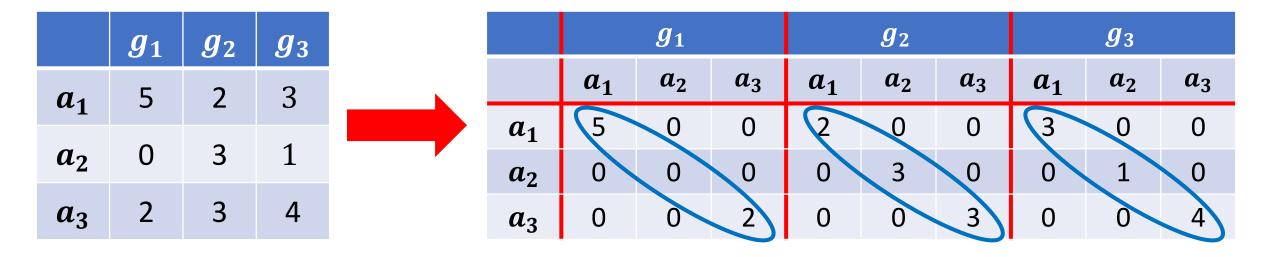
	N	Monday		Tuesday				9	Sunday	
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<i>a</i> ₁	3	1	0	2	5	1	•••	6	5	5
<i>a</i> ₂	2	2	1	3	4	1		2	4	3
<i>a</i> ₃	0	0	4	4	3	2		5	4	5

Item Allocation as a Special Case

• Define the set of issues $T = M = \{g_1, \dots, g_m\}$

• Alternatives
$$C^t = N = \{a_1, \dots, a_n\}$$

• $u_i^t(a_j) = \begin{cases} v_i(g_t) & \text{if } i = j \\ 0 & \text{if } i \neq j \end{cases}$



Fairness for Public Decisions

- Envy-freeness (and relaxations) not sensible in the general case
 - > Decisions are public, all agents receive the same outcome
- Proportionality is still sensible
 - > Each agent should receive their "dictator utility" multiplied by 1/n
- Proportionality up to one *issue* (Prop1)
 - Each agent would receive their proportional share if they were allowed to change the outcome on a single issue
- Theorem [Conitzer et al. 2017]:
 - The MNW outcome satisfies Prop1 + PO in the public decisions setting
- Other fairness desiderata ((approximate) core, round robin share,...)

Allocation of Public Goods

		lssue 1	_		lssue 2	2
	c_{1}^{1}	c_{2}^{1}	c_{3}^{1}	c_{1}^{2}	c_{2}^{2}	c_{3}^{2}
<i>a</i> ₁	3	1	0	2	5	1
<i>a</i> ₂	2	2	1	3	4	1
a_3	0	0	4	4	3	2

- Generalizes public decisions
- A set of public goods $\{g_1, \dots, g_m\}$
 - > Each good can give a positive utility to multiple agents simultaneously
- Constraints on which subsets of public goods are feasible

Allocation of Public Goods

	lssue 1			lssue 2		
	<i>c</i> ¹ ₁	c_{2}^{1}	c_{3}^{1}	c_{1}^{2}	c_{2}^{2}	c_{3}^{2}
<i>a</i> ₁	3	1	0	2	5	1
a_2	2	2	1	3	4	1
a_3	0	0	4	4	3	2

- Public decision example:
 - > Exactly one of $\{g_1, g_2, g_3\}$ and exactly one of $\{g_4, g_5, g_6\}$ must be chosen
 - Partition matroid constraint

Fairness Guarantees

• (δ, α) -Core

- An allocation of public goods C is in S ⊆ N, there is no feasible allocation of public goods C' such that $\frac{|S|}{n} \cdot u_i(C') \ge u_i(C)$ for all i ∈ S, and at least one inequality is strict.
- Valuations are normalized so that $\max_{i} u_i(g_i) = 1$
- Core (i.e. (0,0)-core) generalizes proportionality
 > (0,1)-core generalizes a guarantee very similar to Prop1

Fair Allocation of Public Goods

Matroid constraints

- > Public goods are ground set elements
- > Feasible allocations are basis of a matroid
- > Generalizes public decisions (thus goods allocation) and multiwinner voting

• Theorem [Fain et al. 2018]

- > For matroid constraints, a (0,2)-core allocation exists, and for constant $\epsilon > 0$, a $(0,2 + \epsilon)$ -core allocation can be computed in polynomial time.
- > Algorithm: Maximize smooth Nash welfare $\prod_{i \in N} (1 + u_i(C))$
- > For $\epsilon > 0$, $(0, 1 \epsilon)$ -core allocations may not exist.

Open Problem: Does there always exist a (0,1)-core allocation?

Fair Allocation of Public Goods

• Theorem [Fain et al. 2018]

- ≻ For "matching constraints" and constant $\delta \in (0,1]$, a $(\delta, 8 + 6/\delta)$ -core allocation can be computed in polynomial time.
- > Algorithm: Maximize a slightly different smooth NW $\prod_{i \in N} (1 + 4/\delta + u_i(C))$
- > For $\delta > 0$ and $\alpha < 1$, a (δ, α) -core allocation may not exist.
- > Open problem: Does there always exist a (0,1)-core allocation?
- A slightly worse guarantee with logarithmically large α in case of "packing constraints"

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